

14.4 Tangent Planes and Linear Approximations

Several very close definitions are formulated in this section:

a) Tangent plane to the surface S defined as $z = f(x, y)$ at the point $P(x_0, y_0, z_0)$, $z_0 = f(x_0, y_0)$.

b) Linear approximation to the function f at (x_0, y_0) .

c) $f(x, y)$ differentiable at (x_0, y_0) .

d) Differential dz for a differentiable function

$$z = f(x, y)$$

It is also called total differential.

Consider the function

$$z = f(x, y) = e^{-x^2} + e^{-4y^2}$$

- i) Obtain parametric equations for the curve C_1 of intersection of the surface S represented by f with the plane $y=0$.
- ii) Compute the tangent vector $\vec{V}_1$ for C_1 at the point $P(-1, 0, f(-1, 0))$.
- iii) Obtain parametric equations for the curve C_2 of intersection of the surface S with the plane $x=-1$.
- iv) Compute the tangent vector $\vec{V}_2$ for C_2 at the point $P(-1, 0, f(-1, 0))$.
- v) Construct the plane that contains the two vectors: $\vec{V}_1$ and $\vec{V}_2$.

i) The Curve C_1 (Intersection of S with plane $y=0$)

$$x=x, \quad y=0, \quad z=f(x,0)=e^{-x^2}+1.$$

Introducing a parameter t

$$C_1: \quad x(t)=t, \quad y(t)=0, \quad z(t)=e^{-t^2}+1$$

Therefore,

$$\begin{aligned}\vec{r}_1(t) &= \langle t, 0, e^{-t^2}+1 \rangle \\ \vec{r}_1'(t) &= \langle 1, 0, -2te^{-t^2} \rangle\end{aligned}$$

ii) Tangent vector $\vec{V}_1$ of C_1 at $(-1, 0, f(-1, 0))$.

Notice that $x=-1$ at $t=-1$

Then,

$$\vec{V}_1 = \langle 1, 0, 2e^{-1} \rangle$$

$$\vec{r}_1'(-1)$$

iii) The curve C_2

$$x=-1, \quad y=y, \quad z=f(-1,y)=e^{-1}+e^{-4y^2}$$

Then

$$C_2: \quad x(t)=-1, \quad y(t)=t, \quad z(t)=e^{-1}+e^{-4t^2}$$

$$\vec{r}_2(t) = \langle -1, t, e^{-1}+e^{-4t^2} \rangle$$

$$\vec{r}_2'(t) = \langle 0, 1, -8te^{-4t^2} \rangle$$

iv) Tangent vector $\vec{V}_2$ of C_2 at $(-1, 0, f(-1, 0))$.

$$\vec{V}_2 = \langle 0, 1, 0 \rangle = \vec{r}_2'(0)$$

$y=0$ at $t=0$

v) Plane containing $\vec{V}_1$ and $\vec{V}_2$.

$$\vec{n} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 0 & 2e^{-1} \\ 0 & 1 & 0 \end{vmatrix} = -2e^{-1}\hat{i} + \hat{j} = \langle -2e^{-1}, 0, 1 \rangle$$

Plane with normal $\vec{n}$ passing through $P(-1, 0, f(-1, 0))$.

$$\text{Since } f(-1, 0) = e^{-1} + 1$$

$$P(-1, 0, e^{-1} + 1).$$

Therefore, the plane is given by

$$-2e^{-1}(x+1) + z - (e^{-1} + 1) = 0$$

$$\text{or } -2e^{-1}x + z = e^{-1} + 1 + 2e^{-1} = 3e^{-1} + 1$$

$$\text{or } \boxed{-2e^{-1}x + z = 3e^{-1} + 1} \quad (4.1)$$

Tangent Plane to a surface S represented by $z = f(x, y)$, $(x, y) \in D$ at $P_0(x_0, y_0, z_0)$

First, give definition 6 (Latex Document).

Derivation of the equation for Tangent plane.

a) Curve C_1 intersection of plane $y = y_0$ with S .

$$C_1: \begin{array}{ccc} x = x, & y = y_0, & z = f(x, y_0) \\ \text{Varies} & \text{fixed} & \downarrow \downarrow \text{fixed} \\ & \text{parametric equ. for } C_1 & \text{Varies} \end{array}$$

$$X(x) = x, \quad Y(x) = y_0, \quad Z(x) = f(x, y_0).$$

b) Curve C_2 intersection of plane $x = x_0$ with S .

$$C_2: \begin{array}{c} \text{parametric equ. for } C_2 \\ X(y) = x_0, \quad Y(y) = y, \quad Z(y) = f(x_0, y) \end{array}$$

These two curves pass through the point $(x_0, y_0, f(x_0, y_0))$

Show MAPLE EXAMPLE for
 $f(x, y) = e^{-x^2} + e^{-4y^2}$

Corresponding Vector equations

$$C_1: \vec{r}_1(x) = \langle x, y_0, f(x, y_0) \rangle,$$

$$C_2: \vec{r}_2(y) = \langle x_0, y, f(x_0, y) \rangle$$

Tangent Vector to C_1 at $P_0(x_0, y_0, f(x_0, y_0))$

$$\vec{r}_1'(x) = \langle 1, 0, \frac{\partial f}{\partial x}(x, y_0) \rangle$$

$$\Rightarrow \vec{V}_1 = \vec{r}_1'(x_0) = \langle 1, 0, \frac{\partial f}{\partial x}(x_0, y_0) \rangle$$

Tangent Vector to C_2 at $P_0(x_0, y_0, f(x_0, y_0))$.

$$\vec{r}_2'(y) = \langle 0, 1, \frac{\partial f}{\partial y}(x_0, y) \rangle$$

$$\Rightarrow \vec{V}_2 = \vec{r}_2'(y_0) = \langle 0, 1, \frac{\partial f}{\partial y}(x_0, y_0) \rangle$$

These two tangent Vectors lay in a
Very special plane Tangent Plane.

Equation of Tangent Plane.

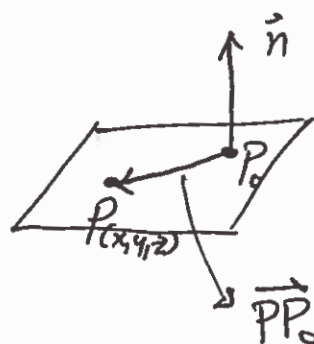
Normal

$$\vec{n} = \vec{V}_1 \times \vec{V}_2 = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 0 & \frac{\partial f}{\partial x}(x_0, y_0) \\ 0 & 1 & \frac{\partial f}{\partial y}(x_0, y_0) \end{vmatrix}$$

$$= -\frac{\partial f}{\partial x}(x_0, y_0) \hat{i} - \frac{\partial f}{\partial y}(x_0, y_0) \hat{j} + 1 \hat{k}$$

Finally, plane containing the two vectors $\vec{V}_1$ and $\vec{V}_2$ and passing through $P_0(x_0, y_0, f(x_0, y_0))$ is given by

$$\vec{PP}_0 \cdot \vec{n} = 0$$



$$\langle x - x_0, y - y_0, z - f(x_0, y_0) \rangle \cdot \left\langle -\frac{\partial f}{\partial x}(x_0, y_0), -\frac{\partial f}{\partial y}(x_0, y_0), 1 \right\rangle = 0$$

$$\Rightarrow -\frac{\partial f}{\partial x}(x_0, y_0)(x - x_0) - \frac{\partial f}{\partial y}(x_0, y_0)(y - y_0) + z - f(x_0, y_0) = 0$$

$$\Rightarrow \boxed{z = f(x_0, y_0) + \frac{\partial f}{\partial x}(x_0, y_0)(x - x_0) + \frac{\partial f}{\partial y}(x_0, y_0)(y - y_0)}$$

0.7 Definition 6: Tangent plane

- Consider a function $f(x, y)$ defined in $\mathcal{D}$ that represents a surface S in $\mathbb{R}^3$.
- This function has continuous first partial derivatives in $\mathcal{D}$.
- Also, $P_0(x_0, y_0, z_0)$ is the center of an open disc $B_r(P_0) \subseteq \mathcal{D}$.
- Let C_1 and C_2 be the two curves obtained by intersecting the surface S with the two planes $x = x_0$ and $y = y_0$, respectively. If T_1 and T_2 are the tangent lines at the point P_0 to the curves C_1 and C_2 , respectively,

then the tangent plane to the surface S at P_0 is defined to be the plane that contains both tangent lines T_1 and T_2 .

0.8 Theorem 2: Equation of the tangent plane

If $f(x, y)$ and the surface S satisfy the conditions of the previous definition then, an equation of the tangent plane to the surface S , represented by the equation $z = f(x, y)$, at the point P_0 is given by

$$z - z_0 = f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0)$$

0.9 Definition 7: Linear approximation of f at (x_0, y_0)

For f satisfying the conditions of Definition 1, we define the *linear approximation of f at (x_0, y_0)* as

$$L(x, y) = f(x_0, y_0) + f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0)$$

0.10 Definition 8: Differentiability

Assume f has partial derivatives at $(x_0, y_0) \in \mathcal{D}$, we will say that f is differentiable at (x_0, y_0) if

$$\Delta z = f(x_0 + \Delta x, y_0 + \Delta y) - f(x_0, y_0) = f_x(x_0, y_0)\Delta x + f_y(x_0, y_0)\Delta y + \epsilon_1\Delta x + \epsilon_2\Delta y,$$

where $\epsilon_1, \epsilon_2 \rightarrow 0$ as $(\Delta x, \Delta y) \rightarrow (0, 0)$

0.11 Theorem 3: Sufficient condition for differentiability

If the partial derivatives f_x and f_y exist near (x_0, y_0) and are continuous at (x_0, y_0) , then f is differentiable at (x_0, y_0) .

Exercise: # 2 (book 9th ed.)

Find equ. of tangent plane to the graph
of Surface: $z = f(x, y) = y^2 \sin x.$

at the point $(\pi/2, -2, 4).$

Tang. plane equ. in general: (at (x_0, y_0, z_0))

$$z = f(x_0, y_0) + \frac{\partial f}{\partial x}(x_0, y_0)(x - x_0) + \frac{\partial f}{\partial y}(x_0, y_0)(y - y_0).$$

In our case,

$$\frac{\partial f}{\partial x}(x, y) = y^2 \cos x, \text{ then } \frac{\partial f}{\partial x}(\pi/2, -2) = 4 \cos(\pi/2) = 0.$$

$$\frac{\partial f}{\partial y}(x, y) = 2y \sin x, \text{ then } \frac{\partial f}{\partial y}(\pi/2, -2) = -4 \sin(\pi/2) = -4$$

Therefore, Tangent Plane is

$$z = 4 + 0(x - \pi/2) - 4(y + 2)$$

or $z + 4y = -4$

Remark: Notice that $\frac{\partial f}{\partial x}$ and $\frac{\partial f}{\partial y}$ are both conts at $(\pi/2, -2)$

Linear Approximation

The tangent plane

$$z + 4y = -4$$

is also called a linear approximation to the function $f(x, y)$ at the point $(x_0, y_0) = (\pi/2, -2)$.

$$L(x, y) = z = -4y - 4$$

The linear approximation ^{at (x_0, y_0)} can be used to approximate the value of the function $f(x, y)$ near the point (x_0, y_0) .

For example, if we want to approximate

$$f(1.4, -1.8) = (-1.8)^2 \sin(1.4).$$

We evaluate

$$L(1.4, -1.8) = -4(-1.8) - 4 = 3.2.$$

While the actual value is given by

$$f(1.4, -1.8) = (-1.8)^2 \sin(1.4) \approx 3.19$$